Comparison of Machine and Human Recognition of Isolated Instrument Tones

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Overview

- Introduction
- Exemplar-based learning
 - k-NN classifier
 - Genetic algorithm
- Machine recognition experiments
- Comparison with human performance
- Conclusions





Introduction

"We tend to think of what we 'really' know as what we can talk about, and disparage knowledge that we can't verbalize." (Dowling 1989, 252)

- Western civilization's emphasis on logic, verbalization, and generalization as signs of intelligence
- Limitation of rule-based learning used in traditional Artificial Intelligence (AI) research
- The lazy learning model is proposed here as an alternative approach to modeling many aspects of music cognition



Traditional AI Research

"In AI generally, and in AI and Music in particular, the acquisition of non-verbal, implicit knowledge is difficult, and no proven methodology exists." (Laske 1992, 259)

- Rule-based approach in traditional AI research
- Exemplar-based learning systems
 - Neural networks (greedy)
 - k-NN classifiers (lazy)
- Adaptive system based on a k-nearest neighbour (k-NN) classifier and a genetic algorithm

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Exemplar-based learning

- The exemplar-based learning model is based on the idea that objects are categorized by their similarity to one or more stored examples
- There is much evidence from psychological studies to support exemplar-based categorization by humans
- This model differs both from rule-based or prototypebased (neural nets) models of concept formation in that it assumes no abstraction or generalizations of concepts
- This model can be implemented using k-nearest neighbour (k-NN) classifier and is further enhanced by application of a genetic algorithm





Applications of lazy learning model

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- Optical music recognition (Fujinaga, Pennycook, and Alphonce 1989; MacMillan, Droettboom, and Fujinaga 2002)
- **Vehicle identification** (Lu, Hsu, and Maldague 1992)
- **Pronunciation** (Cost and Salzberg 1993)
- **Cloud identification** (Aha and Bankert 1994)
- **Respiratory sounds classification** (Sankur et al. 1994)
- Wine analysis and classification (Latorre et al. 1994)
- Robot scene analysis (Schaal et al. 2002)
- Natural language translation (Sato 1995)
- **Tomato classification** (Indriani et al. 2017)







Implementation of lazy learning

- The lazy learning model can be implemented by the k-nearest neighbour classifier (Cover and Hart 1967)
- A classification scheme to determine the class of a given sample by its feature vector
- The class represented by the majority of k-nearest neighbours (k-NN) is then assigned to the unclassified sample
- Besides its simplicity and intuitive appeal, the classifier can be easily modified, by continually adding new samples that it "encounters" into the database, to become an incremental learning system
- Criticisms: slow and high memory requirement





K-nearest neighbour classifier

"The nearest neighbor algorithm is one of the simplest learning methods known, and yet no other algorithm has been shown to outperform it consistently." (Cost and Salzberg 1993)

- The K-NN classifier is the simplest of all machine learning classifiers
- It is based on the principle that things that are similar, are close by



K-nearest neighbour classifier

"Many sophisticated classification algorithms have been proposed... According to our experiments on the popular datasets, k-NN with properly tuned parameters performs on average best." (Kordos, Blachnik & Strzempa 2010)

- Determine the class of a given sample by its feature vector:
 - Distances between feature vectors of an unclassified sample and previously classified samples are calculated
 - The class represented by the majority of k-nearest neighbours is then assigned to the unclassified sample





An example of k-NN classifier Basketball players and Sumo wrestlers



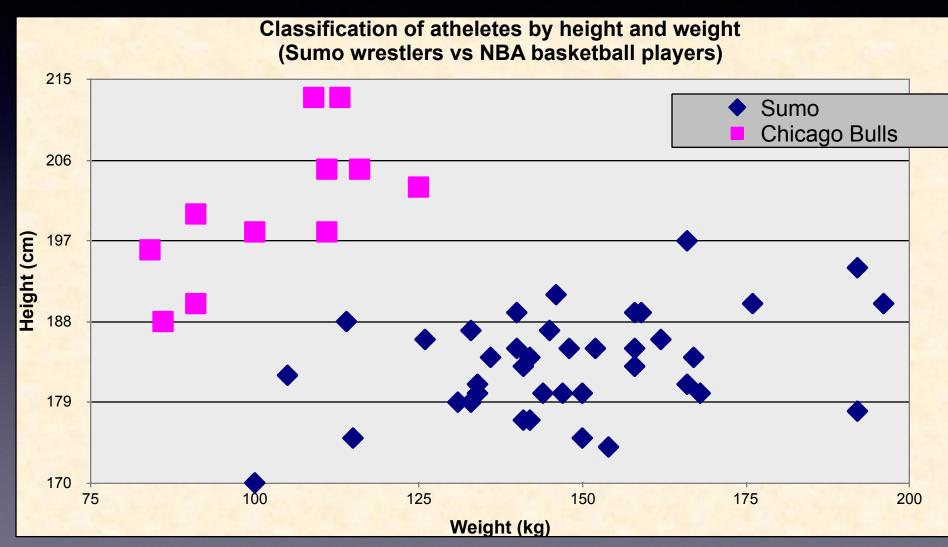
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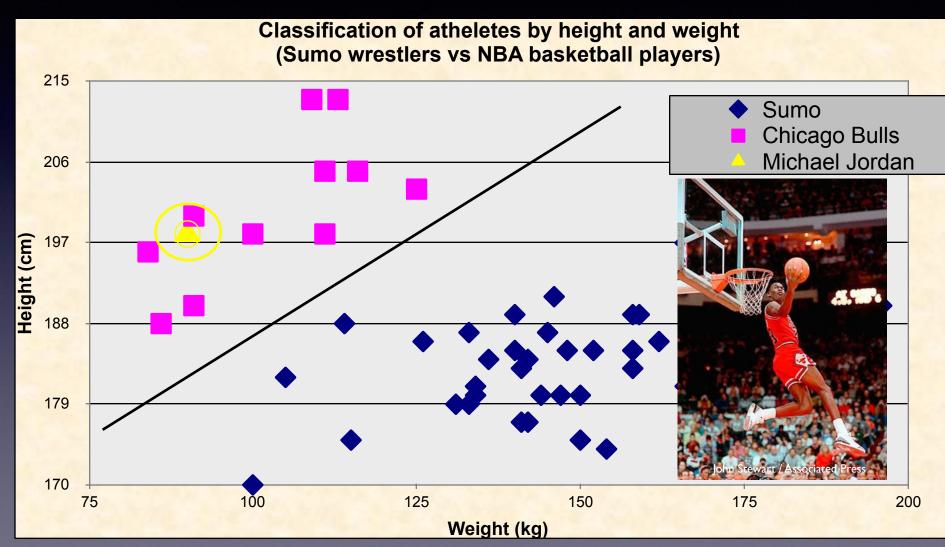
An example of k-NN classifier







Example of k-NN classifier Classifying Michael Jordan

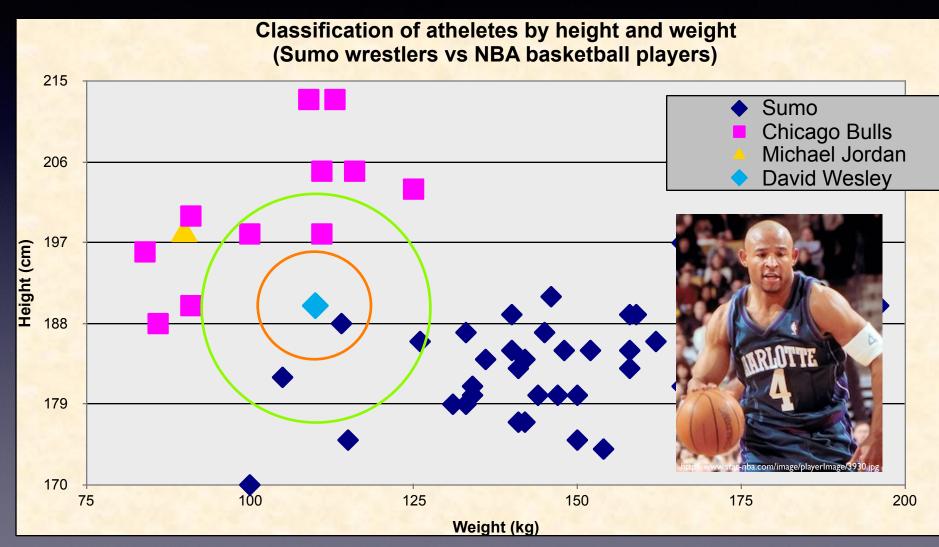








Example of k-NN classifier Classifying David Wesley



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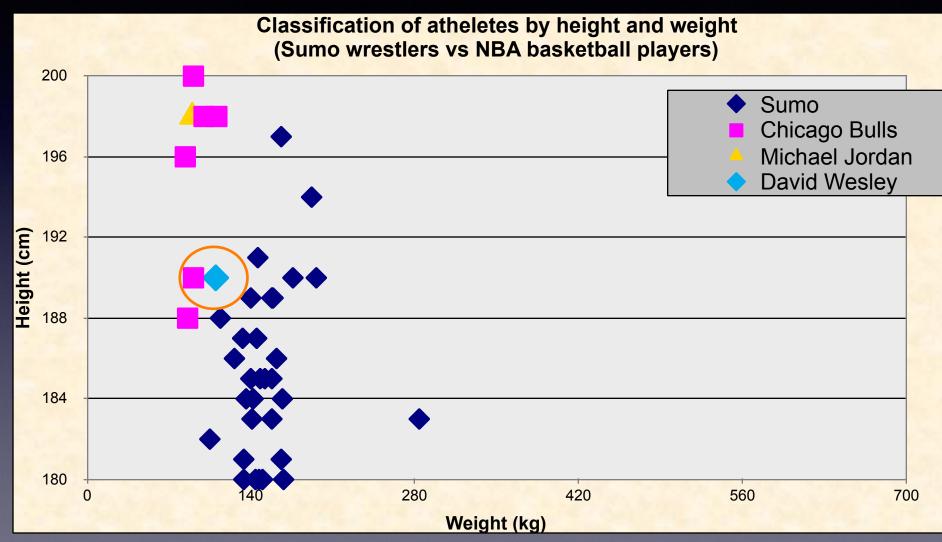






Example of k-NN classifier

Reshaping the Feature Space







Distance measures

 The distance in a N-dimensional feature space between two vectors X and Y can be defined as:

$$d = \sum_{i=0}^{N-1} |x_i - y_i|$$

A weighted distance can be defined as:

$$d = \sum_{i=0}^{N-1} w_i |x_i - y_i|$$





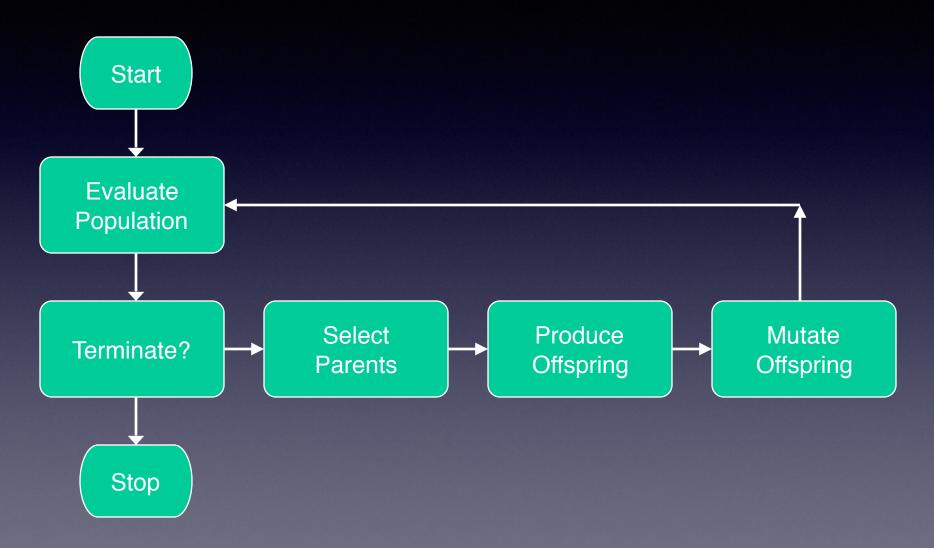
Genetic algorithms

- Optimization based on biological evolution
- Maintenance of population using selection, crossover, and mutation
- Chromosomes = weight vector
- Fitness function = recognition rate
- Leave-one-out cross validation





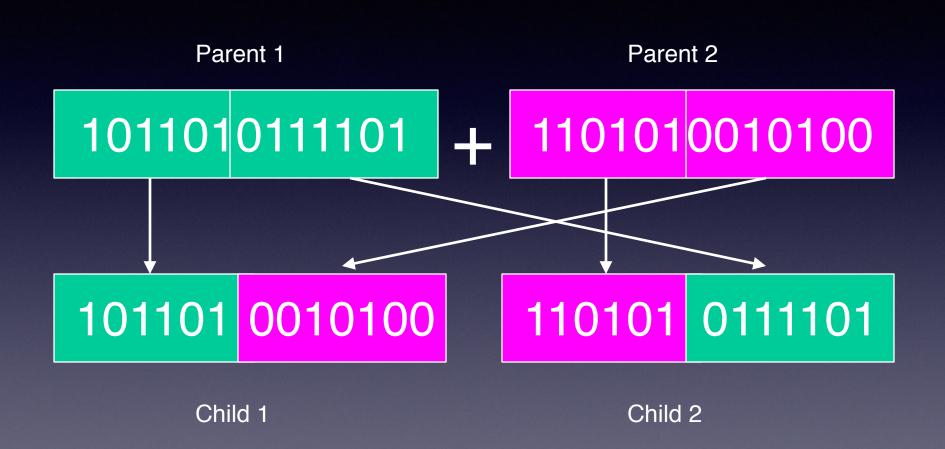
Genetic Algorithm







Crossover in Genetic Algorithm







Applications of Genetic Algorithm in Music

- Instrument design (Horner et al. 1992, Horner et al. 1993, Takala et al. 1993, Vuori and Välimäki 1993, Poirson et al. 2007)
- Compositional aid (Horner and Goldberg 1991, Biles 1994, Johanson and Poli 1998, Wiggins 1998, Geem et al. 2001)
- Expressive music performance (Ramirez and Hazan 2005)
- Granular synthesis regulation (Fujinaga and Vantomme 1994)
- Optimal placement of microphones (Wang 1996)





Realtime Timbre Recognition

- Original source: McGill Master Samples
- Up to over 1300 notes from 39 different timbres (23) orchestral instruments)
- Spectrum analysis of first 232ms of attack (9 overlapping windows)
- Each analysis window (46 ms) consists of a list of amplitudes and frequencies in the spectra

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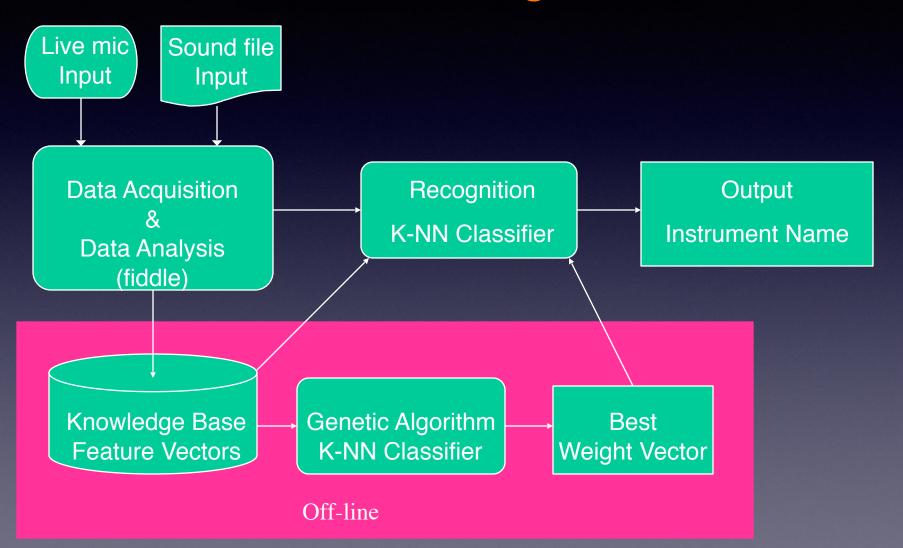
Features

- Static features (per window)
 - pitch •
 - mass or the integral of the curve (zeroth-order moment) •
 - centroid (first-order moment) •
 - variance (second-order central moment) •
 - skewness (third-order central moment) •
 - amplitudes of the harmonic partials
 - number of strong harmonic partials
 - spectral irregularity
 - tristimulus
- Dynamic features
 - means and velocities of static features over time





Overall Architecture for Timbre Recognition

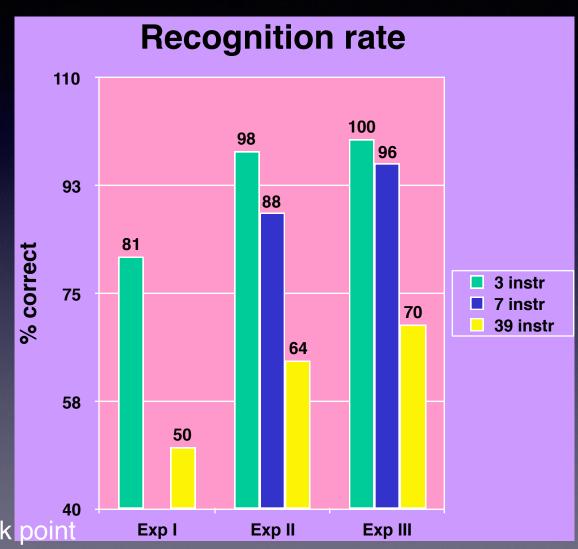






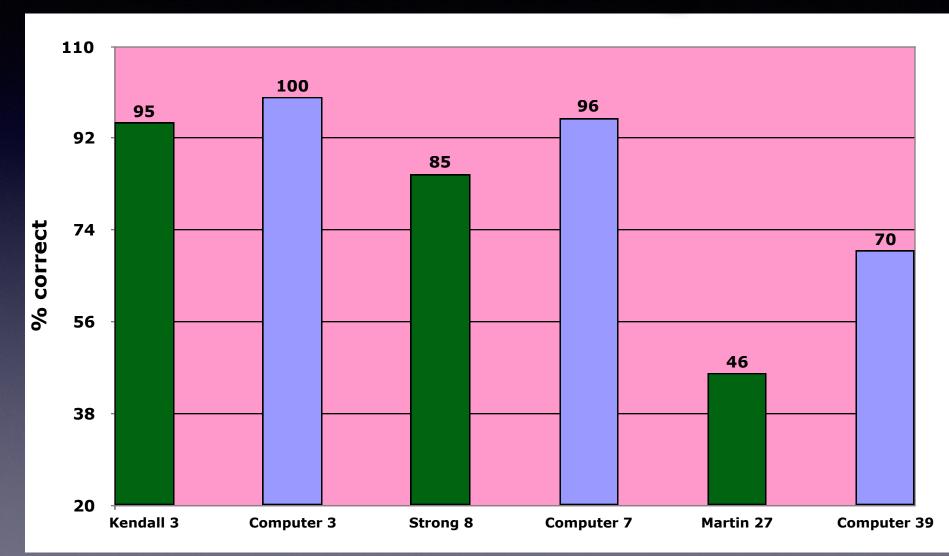
Results

- Experiment I
 - SHARC data
 - static features
- Experiment II
 - McGill samples
 - Fiddle
 - dynamic features
- Experiment III
 - more features
 - redefinition of attack point





Human vs Computer







Peabody experiment

- 88 subjects (undergrad, composition students and faculty)
- Source: McGill Master Samples
- 2-instruments (oboe, saxophones)
- 3-instruments (clarinet, trumpet, violin)
- 9-instruments (flute, oboe, clarinet, bassoon, saxophone, trombone, trumpet, violin, cello)
- 27-instruments:
 - violin, viola, cello, bass
 - piccolo, flute, alto flute, bass flute
 - oboe, english horn, bassoon, contrabassoon
 - Eb clarinet, Bb clarinet, bass clarinet, contrabass clarinet

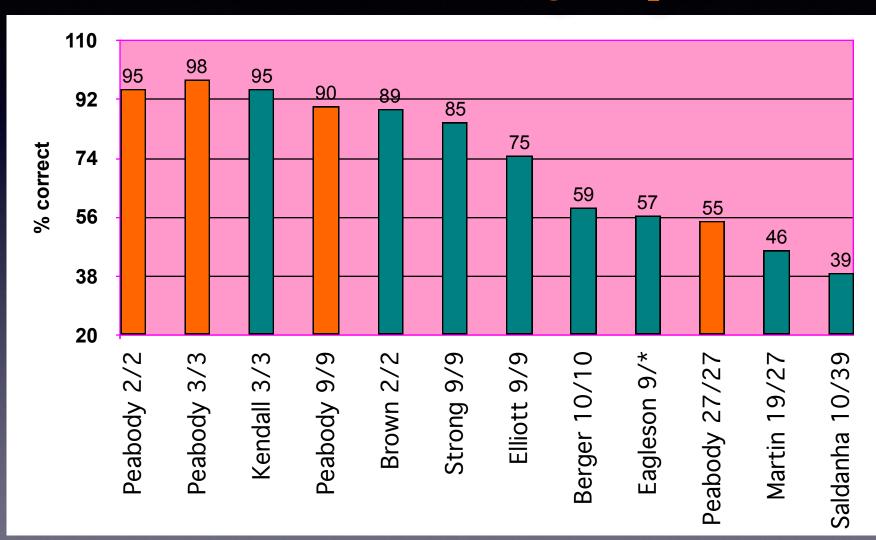
- saxes: soprano, alto, tenor, baritone, bass
- trumpet, french horn, tuba
- trombones: alto, tenor, bass







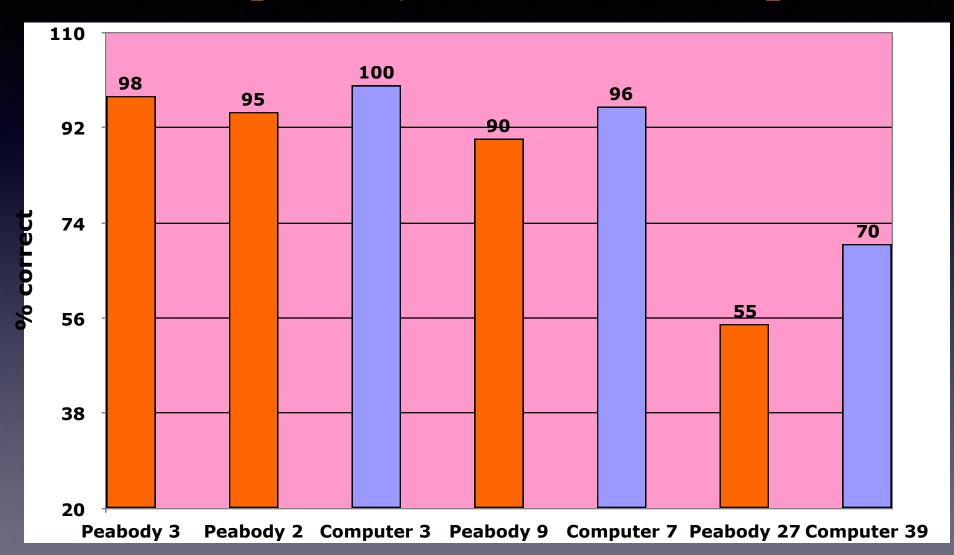
Peabody vs other human groups







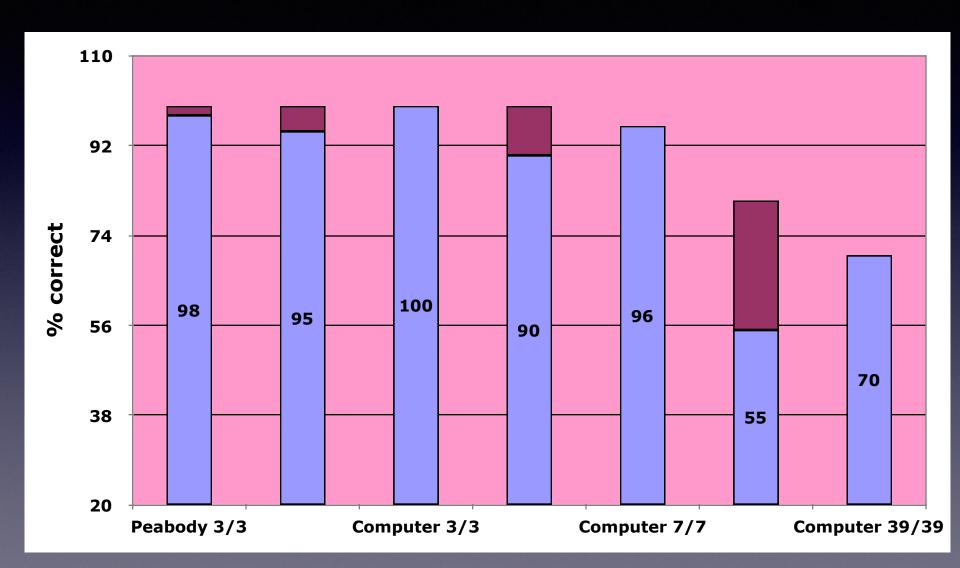
Peabody subjects vs Computer







The best Peabody subjects vs Computer







Future Research for Timbre Recognition

- Performer identification
- Speaker identification
- Tone-quality analysis
- Multi-instrument recognition
- Expert recognition of timbre





Conclusions

- Realtime adaptive timbre recognition by k-NN classifier enhanced with genetic algorithm
- A successful implementation of the exemplarbased learning system in a time-critical environment
- Recent human experiments poses new challenges for machine recognition of isolated tones











Recognition rate for different lengths of analysis window

